

Embedding Fault-Tolerance, Exploiting Approximate Computing and Retaining High Performance in the Matrix Multiplication

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Matrix multiplication (GEMM)

"Fault-tolerant high-performance matrix-matrix multiplication: theory and practice" John A. Gunnels, Daniel S. Katz, Enrique S. Quintana, Robert van de Geijn Int. Conference on Dependable Systems and Networks - DSN 2001

Provide a software layer for reliability in numerical libraries for spaceborne missions

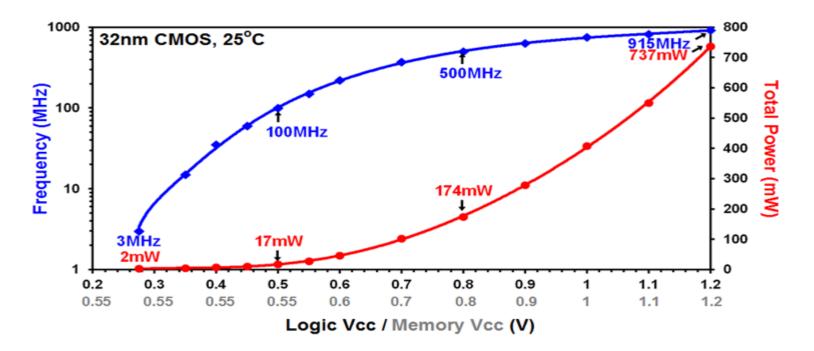




Motivation



- Fault tolerance for GEMM, revisited
 - Near-threshold voltage computing (NTVC) reduces power...



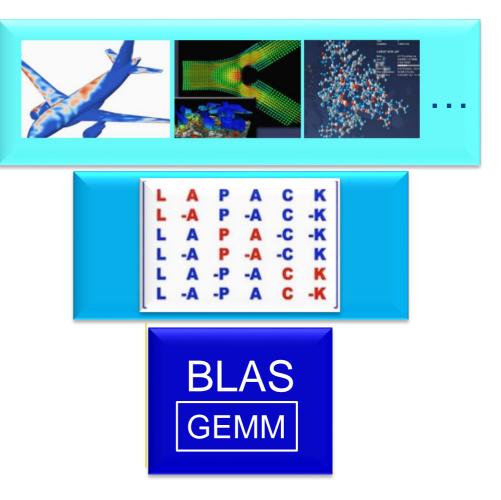
at the cost of increasing error rates

Motivation



• Why GEMM?

- Many scientific and engineering computations can be decomposed into a reduced number of linear algebra operations
- Most dense linear algebra operations can be cast in terms of GEMM

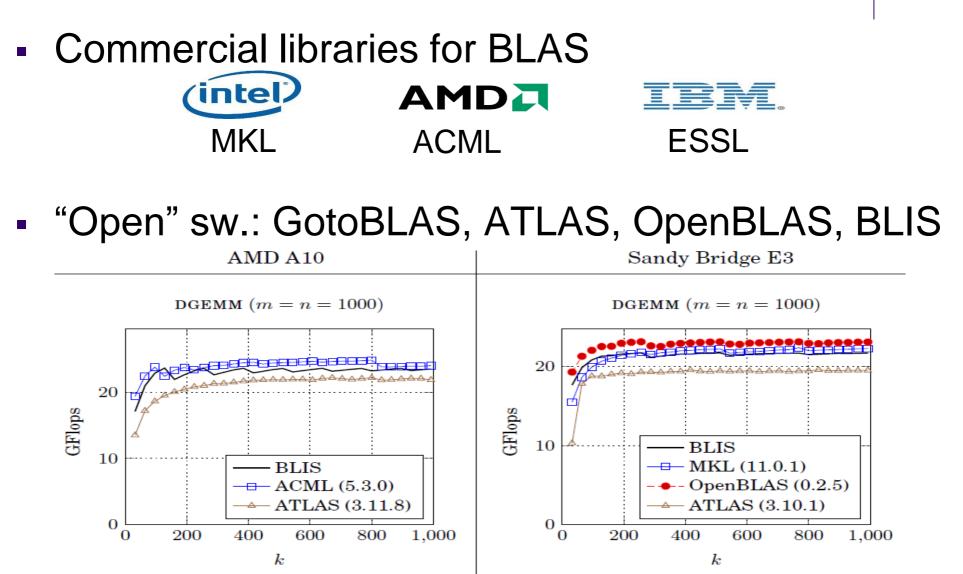




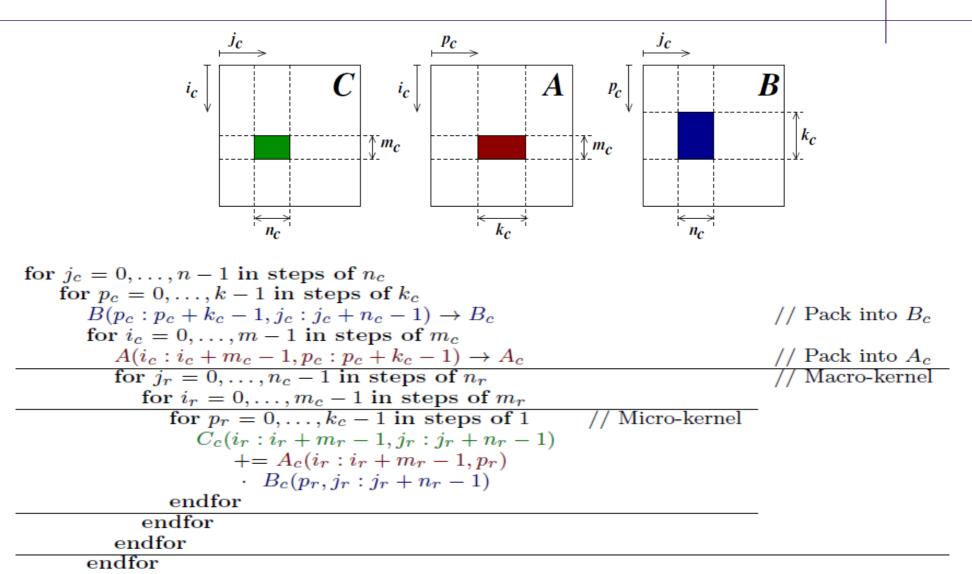


- High performance GEMM
- Fault tolerance (FT) vs approx. computing (AC)
- Embedding FT/AC in high performance GEMM
- Experimental results
- Concluding remarks





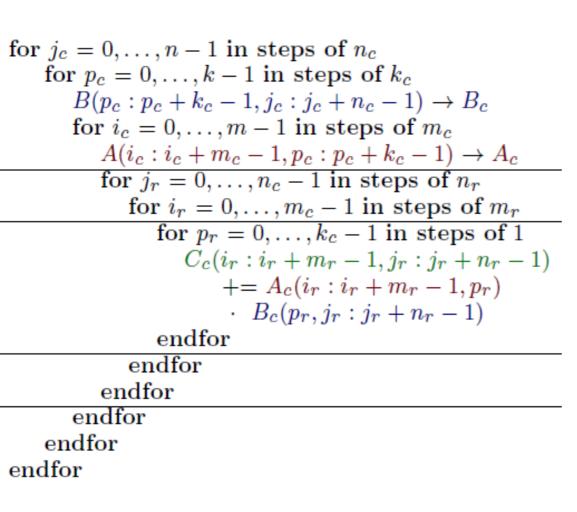


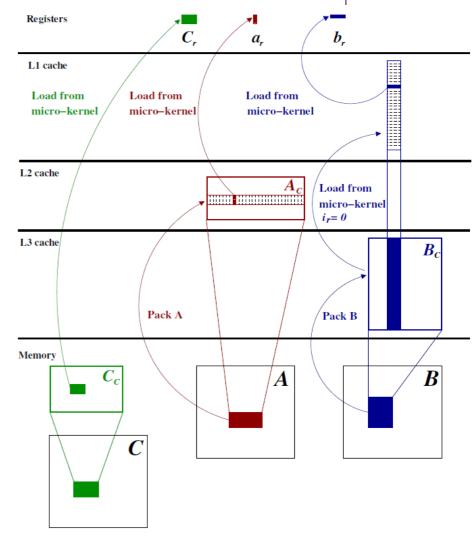


endfor

 \mathbf{endfor}









• Consider C = A B, and the augmented matrices

$$A^* = \left(\frac{A}{v^T A}\right), \quad B^* = \left(\begin{array}{c|c} B & Bw \end{array}\right), \quad C^* = \left(\frac{C}{v^T C} & Cw \\ \hline v^T C & v^T Cw \end{array}\right),$$

In absence of error, then $C^* = A^* B^*$. Use *left and right checksum* vectors:

$$\begin{aligned} \|d\|_{\infty} &= \|C \cdot w - A \cdot (B \cdot w)\|_{\infty} > 0 \quad \text{or} \\ \|e^{T}\|_{\infty} &= \|v^{T} \cdot C - (v^{T} \cdot A) \cdot B\|_{\infty} > 0. \end{aligned}$$

"Algorithm-based fault tolerance for matrix operations" K.-H. Huang and J. A. Abraham IEEE Transactions on Computers, vol. 33, no. 6, pp. 518–528, 1984.



In practice, due to finite precision arithmetic, an error is detected if

$$\begin{aligned} \|d\|_{\infty} &> \tau \cdot \|A\|_{\infty} \cdot \|B\|_{\infty} \\ \|e^{T}\|_{\infty} &> \tau \cdot \|A\|_{\infty} \cdot \|B\|_{\infty}, \end{aligned}$$

where $\tau = \max(m, n, k) \cdot u$ for FT

"Fault-tolerant high-performance matrix-matrix multiplication: theory and practice" John A. Gunnels, Daniel S. Katz, Enrique S. Quintana, Robert van de Geijn Int. Conference on Dependable Systems and Networks - DSN 2001

or higher for AC!



Overhead for full GEMM (detection only)

$$\begin{aligned} \|d\|_{\infty} &= \|C \cdot w - A \cdot (B \cdot w)\|_{\infty} \\ \|e^{T}\|_{\infty} &= \|v^{T} \cdot C - (v^{T} \cdot A) \cdot B\|_{\infty} \end{aligned}$$

$$\mathcal{O}_d(m, n, k) = \frac{4mn + 5mk + 5kn}{\mathcal{O}_c(m, n, k)} = \frac{4mn + 5mk + 5kn}{2mnk},$$

- Has to be applied off-line
- Requires a copy of the full matrix *C*
- Correction is expensive: recompute the full product

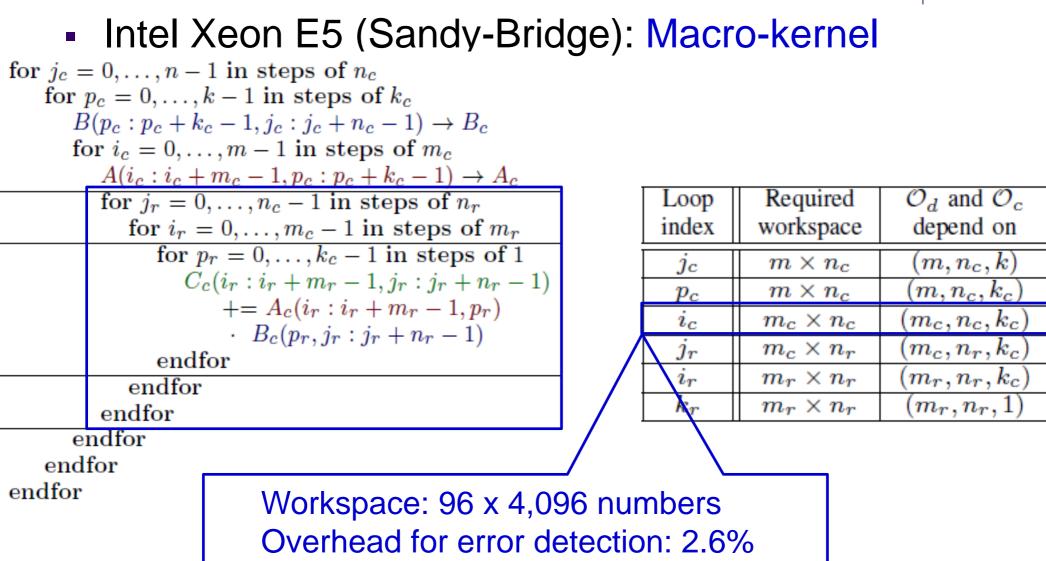


Apply with smaller granularity

for $j_c = 0, \ldots, n-1$ in steps of n_c for $p_c = 0, \ldots, k-1$ in steps of k_c $B(p_c: p_c + k_c - 1, j_c: j_c + n_c - 1) \rightarrow B_c$ for $i_c = 0, \ldots, m-1$ in steps of m_c $\begin{array}{l} A(i_c:i_c+m_c-1,p_c:p_c+k_c-1) \to A_c \\ \text{for } j_r = 0, \dots, n_c-1 \text{ in steps of } n_r \end{array}$ for $i_r = 0, \ldots, m_c - 1$ in steps of m_r for $p_r = 0, \ldots, k_c - 1$ in steps of 1 $C_c(i_r:i_r+m_r-1,j_r:j_r+n_r-1)$ $+= A_c(i_r: i_r + m_r - 1, p_r)$ $\cdot B_{c}(p_{r}, j_{r}: j_{r} + n_{r} - 1)$ endfor endfor endfor endfor endfor endfor

Loop	Required	\mathcal{O}_d and \mathcal{O}_c
index	workspace	depend on
j_c	$m imes n_c$	(m, n_c, k)
p_c	$m imes n_c$	(m, n_c, k_c)
i_c	$m_c imes n_c$	(m_c, n_c, k_c)
j_r	$m_c imes n_r$	(m_c, n_r, k_c)
i_r	$m_r imes n_r$	(m_r,n_r,k_c)
k_r	$m_r imes n_r$	$(m_r, n_r, 1)$





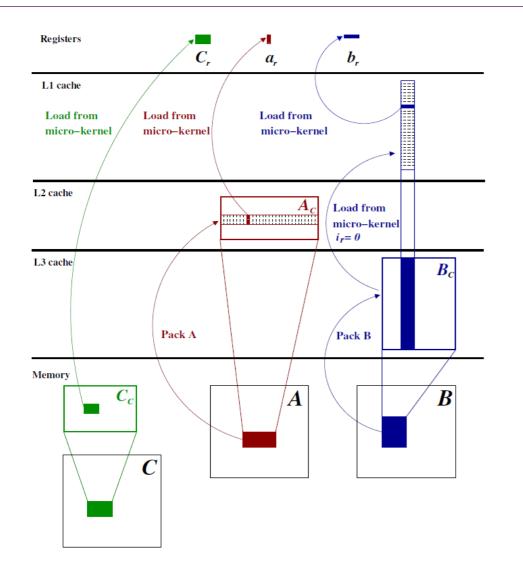


for
$$j_c = 0, \dots, n-1$$
 in steps of n_c
for $p_c = 0, \dots, k-1$ in steps of k_c
 $B(p_c : p_c + k_c - 1, j_c : j_c + n_c - 1) \rightarrow B_c$
for $i_c = 0, \dots, m-1$ in steps of m_c
 $A(i_c : i_c + m_c - 1, p_c : p_c + k_c - 1) \rightarrow A_c$
for $j_r = 0, \dots, n_c - 1$ in steps of n_r
for $i_r = 0, \dots, m_c - 1$ in steps of 1
 $C_c(i_r : i_r + m_r - 1, j_r : j_r + n_r - 1)$
 $+= A_c(i_r : i_r + m_r - 1, p_r)$
 $\cdot B_c(p_r, j_r : j_r + n_r - 1)$
endfor
endfor
endfor
endfor
endfor

$$\begin{aligned} \|d\|_{\infty} &= \|C \cdot w - A \cdot (B \cdot w)\|_{\infty} \\ |e^{T}\|_{\infty} &= \|v^{T} \cdot C - (v^{T} \cdot A) \cdot B\|_{\infty} \end{aligned}$$

with $C = C_c$, $A = A_c$, $B = B_c$ (macro-kernel)





$$\begin{aligned} \|d\|_{\infty} &= \|C \cdot w - A \cdot (B \cdot w)\|_{\infty} \\ |e^{T}\|_{\infty} &= \|v^{T} \cdot C - (v^{T} \cdot A) \cdot B\|_{\infty} \end{aligned}$$

with $C = C_c$, $A = A_c$, $B = B_c$ (macro-kernel)



• Left checksum: $d = \hat{C}_c \cdot w - A_c \cdot B_c \cdot w$

for $j_c = 0, ..., n - 1$ in steps of $n_c, J_c = j_c : j_c + n_c - 1$ for $p_c = 0, ..., k - 1$ in steps of $k_c, \mathcal{P}_c = p_c : p_c + k_c - 1$ $B(\mathcal{P}_c, \mathcal{J}_c) \to B_c$ $d_h = -B_c \cdot w$ for $i_c = 0, ..., m - 1$ in steps of $m_c, I_c = i_c : i_c + m_c - 1$ $A(\mathcal{I}_c, \mathcal{P}_c) \to A_c$ $d = A_c \cdot d_b \ (= A_c \cdot B_c \cdot d_b)$ $e_a^T = -v^T \cdot A_c$ for $j_r = 0, ..., n_c - 1$ in steps of $n_r, \mathcal{J}_r = j_r : j_r + n_r - 1$ $e^T(\mathcal{J}_r) = e_c^T \cdot B_c(0:k_c-1,\mathcal{J}_r)$ for $i_r = 0, ..., m_c - 1$ in steps of $m_r, \mathcal{I}_r = i_r : i_r + m_r - 1$ $\hat{C}_c(\mathcal{I}_r, \mathcal{J}_r) = A_c(\mathcal{I}_r, 0: k_c - 1) \cdot B_c(0: k_c - 1, \mathcal{J}_r)$ $d(\mathcal{I}_r) += \hat{C}_c(\mathcal{I}_r, \mathcal{I}_r) \cdot w(\mathcal{I}_r)$ $e^{T}(\mathcal{J}_{r}) + = v^{T}(\mathcal{I}_{r}) \cdot \hat{C}_{c}(\mathcal{I}_{r}, \mathcal{J}_{r})$ endfor endfor if $(\|d\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty})$ or $(\|e_c^T\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty})$ recompute macro-kernel else $C(\mathcal{I}_c, \mathcal{J}_c) + = \hat{C}_c$ endif endfor endfor endfor



• Right checksum: $e^T = v^T \cdot \hat{C}_c - v^T \cdot A_c \cdot B_c$

for $j_c = 0, ..., n - 1$ in steps of $n_c, J_c = j_c : j_c + n_c - 1$ for $p_c = 0, ..., k - 1$ in steps of $k_c, \mathcal{P}_c = p_c : p_c + k_c - 1$ $B(\mathcal{P}_c, \mathcal{J}_c) \to B_c$ $d_h = -B_c \cdot w$ for $i_c = 0, ..., m - 1$ in steps of $m_c, \mathcal{I}_c = i_c : i_c + m_c - 1$ $A(\mathcal{I}_c, \mathcal{P}_c) \to A_c$ $d = A_c \cdot d_b \ (= A_c \cdot B_c \cdot d_b)$ $e_a^T = -v^T \cdot A_c$ for $j_r = 0, ..., n_c - 1$ in steps of $n_r, \mathcal{J}_r = j_r : j_r + n_r - 1$ $e^T(\mathcal{J}_r) = e_c^T \cdot B_c(0:k_c-1,\mathcal{J}_r)$ for $i_r = 0, ..., m_c - 1$ in steps of $m_r, I_r = i_r : i_r + m_r - 1$ $\hat{C}_c(\mathcal{I}_r, \mathcal{J}_r) = A_c(\mathcal{I}_r, 0: k_c - 1) \cdot B_c(0: k_c - 1, \mathcal{J}_r)$ $d(\mathcal{I}_r) += \hat{C}_c(\mathcal{I}_r, \mathcal{I}_r) \cdot w(\mathcal{I}_r)$ $e^{T}(\mathcal{J}_{r}) + = v^{T}(\mathcal{I}_{r}) \cdot \hat{C}_{c}(\mathcal{I}_{r}, \mathcal{J}_{r})$ endfor endfor if $(\|d\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty})$ or $(\|e_c^T\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty})$ recompute macro-kernel else $C(\mathcal{I}_c, \mathcal{J}_c) + = \hat{C}_c$ endif endfor endfor endfor

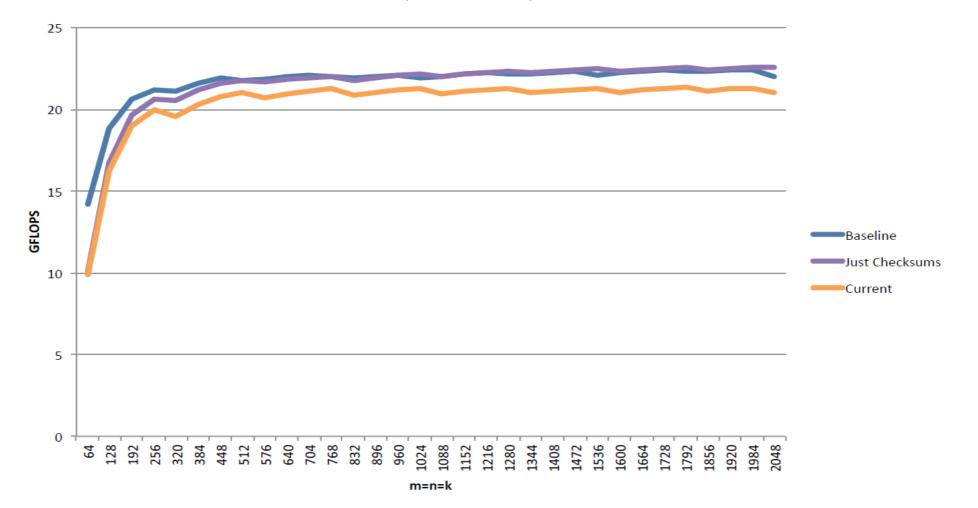


• Detect and prevent error: Check $||d||_{\infty}$ and $||e^{T}||_{\infty}$

```
for j_c = 0, ..., n - 1 in steps of n_c, J_c = j_c : j_c + n_c - 1
    for p_c = 0, ..., k - 1 in steps of k_c, \mathcal{P}_c = p_c : p_c + k_c - 1
        B(\mathcal{P}_c, \mathcal{J}_c) \to B_c
        d_h = -B_c \cdot w
        for i_c = 0, ..., m - 1 in steps of m_c, \mathcal{I}_c = i_c : i_c + m_c - 1
           A(\mathcal{I}_c, \mathcal{P}_c) \to A_c
           d = A_c \cdot d_b \ (= A_c \cdot B_c \cdot d_b)
           e_a^T = -v^T \cdot A_c
           for j_r = 0, ..., n_c - 1 in steps of n_r, \mathcal{J}_r = j_r : j_r + n_r - 1
              e^T(\mathcal{J}_r) = e_c^T \cdot B_c(0:k_c-1,\mathcal{J}_r)
              for i_r = 0, ..., m_c - 1 in steps of m_r, \mathcal{I}_r = i_r : i_r + m_r - 1
                  \hat{C}_c(\mathcal{I}_r, \mathcal{J}_r) = A_c(\mathcal{I}_r, 0: k_c - 1) \cdot B_c(0: k_c - 1, \mathcal{J}_r)
                  d(\mathcal{I}_r) \mathrel{+}= \hat{C}_c(\mathcal{I}_r, \mathcal{J}_r) \cdot w(\mathcal{J}_r)
                  e^{T}(\mathcal{J}_{r}) + = v^{T}(\mathcal{I}_{r}) \cdot \hat{C}_{c}(\mathcal{I}_{r}, \mathcal{J}_{r})
               endfor
           endfor
           if (\|d\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty}) or (\|e_c^T\|_{\infty} > \tau \|A\|_{\infty} \|B\|_{\infty})
              recompute macro-kernel
           else
              C(\mathcal{I}_c, \mathcal{J}_c) + = \hat{C}_c
           endif
        endfor
    endfor
endfor
```



Intel Xeon E5-2680. BLIS (baseline) vs current FT-BLIS





Selective error correction
 Detection at the macro-kernel level:

$$4m_cn_c + 5m_ck_c + 5k_cn_c \qquad \qquad \mathcal{O}_d(m_c, n_c, k_c)$$

but correction can proceed at the micro-kernel level:

$$2m_r n_r k_c$$
 $\mathcal{O}_c(m_r, n_r, k_c)$

instead of

$$2m_c n_c k_c$$

 $\mathcal{O}_c(m_c, n_c, k_c)$



Concluding Remarks

- Easy to integrate FT and AC into the same framework for BLIS
- Left and right checksums yield acceptable overhead for high performance GEMM
- Much work to be done to turn it practical:
 - Multi-threaded GEMM